

Суммарный импульс:

$$Q_x(t) = (Mc + M_{1c}) \frac{d}{dt} x_c(t) + (x_1(t) - r) \frac{d}{dt} M_1(t) + M_1(t) \frac{d}{dt} x_1(t) \quad (1)$$

$$Q_y(t) = (Mc + M_{1c}) \frac{d}{dt} y_c(t) + y_1(t) \frac{d}{dt} M_1(t) + M_1(t) \frac{d}{dt} y_1(t) \quad (2)$$

Производная от суммарного импульса:

$$\frac{d}{dt} Q_x(t) = (M_c + M_{1c}) \frac{d^2}{dt^2} x_c(t) + 2 \left(\frac{d}{dt} x_1(t) \right) \frac{d}{dt} M_1(t) + \left[(x_1(t) - r) \frac{d^2}{dt^2} M_1(t) \right] + M_1(t) \frac{d^2}{dt^2} x_1(t) \quad (3)$$

$$\frac{d}{dt} Q_y(t) = (M_c + M_{1c}) \frac{d^2}{dt^2} y_c(t) + 2 \left(\frac{d}{dt} y_1(t) \right) \frac{d}{dt} M_1(t) + \left[y_1(t) \frac{d^2}{dt^2} M_1(t) \right] + M_1(t) \frac{d^2}{dt^2} y_1(t) \quad (4)$$

Применяя ур-ие Мещерского: учитывая: $\frac{d}{dt} m = \frac{d}{dt} M_1(t)$

$$\frac{d}{dt} Q_x(t) = (M_c + M_{1c}) \frac{d^2}{dt^2} x_c(t) + 2 \left(\frac{d}{dt} x_1(t) \right) \frac{d}{dt} M_1(t) + M_1(t) \frac{d^2}{dt^2} x_1(t) = \left(\frac{d}{dt} m \right) u - \left(\frac{d}{dt} m \right) \left(u - \frac{d}{dt} x_1(t) \right) \quad (5)$$

$$\frac{d}{dt} Q_y(t) = (M_c + M_{1c}) \frac{d^2}{dt^2} y_c(t) + 2 \left(\frac{d}{dt} y_1(t) \right) \frac{d}{dt} M_1(t) + M_1(t) \frac{d^2}{dt^2} y_1(t) = \left(\frac{d}{dt} m \right) u - \left(\frac{d}{dt} m \right) \left(u - \frac{d}{dt} y_1(t) \right) \quad (6)$$

Чуть-чуть развернем, раскроем скобки:

$$\frac{d}{dt} Q_x(t) = (M_c + M_{1c}) \frac{d^2}{dt^2} x_c(t) + \left(\frac{d}{dt} x_1(t) \right) \frac{d}{dt} M_1(t) + \left(\frac{d}{dt} x_1(t) \right) \frac{d}{dt} M_1(t) + M_1(t) \frac{d^2}{dt^2} x_1(t) = \left(\frac{d}{dt} m \right) u - \left(\frac{d}{dt} m \right) u + \frac{d}{dt} x_1(t) \left(\frac{d}{dt} m \right)$$

$$\frac{d}{dt} Q_y(t) = (M_c + M_{1c}) \frac{d^2}{dt^2} y_c(t) + \left(\frac{d}{dt} y_1(t) \right) \frac{d}{dt} M_1(t) + \left(\frac{d}{dt} y_1(t) \right) \frac{d}{dt} M_1(t) + M_1(t) \frac{d^2}{dt^2} y_1(t) = \left(\frac{d}{dt} m \right) u - \left(\frac{d}{dt} m \right) u + \frac{d}{dt} y_1(t) \left(\frac{d}{dt} m \right)$$

После сокращения:

$$\frac{d}{dt}Q_x(t) = (M_c + M_{lc})\frac{d^2}{dt^2}x_c(t) + \left(\frac{d}{dt}x_1(t)\right)\frac{d}{dt}M_1(t) + M_1(t)\frac{d^2}{dt^2}x_1(t) \quad (7)$$

$$\frac{d}{dt}Q_y(t) = (M_c + M_{lc})\frac{d^2}{dt^2}y_c(t) + \left(\frac{d}{dt}y_1(t)\right)\frac{d}{dt}M_1(t) + M_1(t)\frac{d^2}{dt^2}y_1(t) \quad (8)$$

После интегрирования:

$$Q_x(t) = (M_c + M_{lc})\frac{d}{dt}x_c(t) - r\frac{d}{dt}M_1(t) + M_1(t)\frac{d}{dt}x_1(t) \quad (9)$$

$$Q_y(t) = (M_c + M_{lc})\frac{d}{dt}y_c(t) + M_1(t)\frac{d}{dt}y_1(t) \quad (10)$$